Some Properties of Reproducing Kernels on an Infinite Network

Dedicated to Professor Fumi-Yuki Maeda on his 60th birthday

Atsushi MURAKAMI[®], Maretsugu YAMASAKI[®] and Yoshinori YONE-E[®]

a Department of Mathematics, Hiroshima Institute of Technology, Hiroshima, 731-51 JAPAN

and

b Department of Mathematics, Faculty of Science, Shimane University, Matsue, 690 JAPAN (Received September 5, 1994)

It is shown that the extremal length of an infinite network satisfies a triangle inequality. A new formula for the extremal distance between two nodes will be given with the aid of a reproducing kernel. We shall discuss extremum problems related to Green functions.

§1. Introduction

Let $N = \{X, Y, K, r\}$ be an infinite network which is connected and locally finite and has no self-loop as in [5]. Here X is the countable set of nodes, Y is the countable set of arcs, K is the node-arc incidence matrix and r is a strictly positive real valued function on Y. Denote by L(X) (resp. L(Y)) the set of all real valued functions on X (resp. Y) and by $L_0(X)$ (resp. $L_0(Y)$) the set of $u \in L(X)$ (resp. $w \in L(Y)$) with finite support.

The energy H(w) of $w \in L(Y)$ is defind by

$$H(w):=\sum_{y\in Y}r(y)w(y)^2.$$

Let $L_2(Y; r)$ be the set of all $w \in L(Y)$ such that $H(w) < \infty$. For $w_1, w_2 \in L_2(Y; r)$, their inner product $\langle w_1, w_2 \rangle$ is defined by

$$< w_1, w_2 > := \sum_{y \in Y} r(y) w_1(y) w_2(y).$$

For $u \in L(X)$, its discrete derivative $du \in L(X)$, its Dirichlet sum D(u) and its Laplacian $\Delta u \in L(X)$ are defined by

$$du(y) := -r(y)^{-1} \sum_{x \in X} K(x, y) u(x)$$

= $r(y)^{-1} [u(x^{-}(y)) - u(x^{+}(y))],$
 $D(u) := H(du) = \sum_{y \in Y} r(y) [du(y)]^{2},$
 $\Delta u(x) := \sum_{y \in Y} K(x, y) [du(y)],$

where $x^{-}(y)$ (the initial node of y) and $x^{+}(y)$ (the terminal node of y) are determined uniquely by the relation :

$$K(x^{-}(y), y) = -1, K(x^{+}(y), y) = 1.$$

Denote by D(N) the set of all $u \in L(X)$ with finite Dirichlet sum, i.e.,

$$\boldsymbol{D}(N) := \{ u \in L(X); D(u) < \infty \}.$$

For $u, v \in D(N)$, the mutual Dirichlet sum D(u, v) is defined by

$$D(u, v) := \langle du, dv \rangle = \sum_{y \in Y} r(y) [du(y)] [dv(y)].$$

It is well-known that D(N) is a Hilbert space with respect to the inner product :

$$((u, v)) := D(u, v) + u(x_0)v(x_0)$$

with a fixed node x_0 . Denote by $D_0(N)$ the closure of $L_0(X)$ in D(N) with respect to the norm :

$$||u|| := [((u, u))]^{1/2} = [D(u) + u(x_0)^2]^{1/2}.$$

Note that $D_0(N)$ does not depend on the choice of x_0 .

For a fixed node x_0 , put

$$D(N; x_0) := \{ u \in D(N); u(x_0) = 0 \}$$

It is well-known that $D(N; x_0)$ is a Hilbert space with respect to the inner product D(u, v) (cf. [5]). For simplicity, put $X_0 = X - \{x_0\}$. For any $a \in X_0$, u(a) is a continuous linear functional on $D(N; x_0)$. In fact, there exists a constant M by [5; Lemma 1] which depends only on $\{x_0, a\}$ such that

$$|u(a)| \leq M[D(u)]^{1/2}$$
 for every $u \in D(N; x_0)$.

By Riesz representation theorem, there exists a unique reproducing kernel $k_a \in D(N; x_0)$ such that

(K.1)
$$u(a) = D(u, k_a)$$
 for every $u \in D(N; x_0)$.

This k_a is called the Kuramochi kernel in [4].

In case N is of hyperbolic type (of order 2), there exists a unique function $g_a \in D_0$ (N) such that

(G.1)
$$v(a) = D(v, g_a)$$
 for every $v \in D_0(N)$.

This g_a is called the Green function of N with pole at a in [6].

We shall show some roles of reproducing kernels k_a and g_a in the study of extremum problems on an infinite network.

§2. A triangle inequality for the extremal distance

Let a and b be two distinct nodes and denote by $P_{a,b}$ the set of all paths form a to b (cf. [5]).

The extremal distance $\lambda(a, b)$ of N between a and b is defined by

$$\lambda(a, b)^{-1} := \inf\{H(W); W \in EL(\mathbb{P}_{a,b})\},\$$

where $EL(\mathbb{P}_{a,b})$ is the set of all non-negative $W \in L(Y)$ such that

$$\sum_{y \in C_Y(P)} r(y) W(y) \ge 1$$
 for all $P \in \mathbb{P}_{a,b}$,

where $C_{Y}(P)$ is the ordered set of arcs in P (cf. [5]).

By definition, $\lambda(a, b) = \lambda(b, a)$.

We shall be concerned with the following triangle inequality for extremal distance :

(2.1)
$$\lambda(a,b) \leq \lambda(a,c) + \lambda(c,b)$$

for every distinct three nodes a, b and c.

In case N is a finite network, Duffin [1] showed a triangle inequality for the joint resistance.

Let us consider the following extremum problem :

(2.2) Minimize D(u)

subject to $u \in L(X)$, u(a) = 0, u(b) = 1.

Denote by d(a, b) the value of Problem (2.2). Sometimes we call the optimal solution of Problem (2.2) the optimal solution for d(a, b).

The following result was proved by Duffin [2] in case N is a finite network and by Yamasaki [5] in case N is an infinite network.

LEMMA 2.1. $\lambda(a, b) = d(a, b)^{-1}$.

We prepare

LEMMA 2.2. There exists a unique optimal solution \tilde{u} for d(a, b). This \tilde{u} has the following properties :

(2.3) $D(\tilde{u}) < \infty, \ \tilde{u}(a) = 0, \ \tilde{u}(b) = 1;$

(2.4)
$$0 \le \tilde{u}(x) \le 1 \text{ on } X;$$

(2.5)
$$\Delta \tilde{u}(x) = D(\tilde{u}) [\varepsilon_a(x) - \varepsilon_b(x)],$$

where ε_a denotes the characteristic function of $\{a\}$, i.e., $\varepsilon_a(x) = 0$ for $x \neq a$ and $\varepsilon_a(a) = 1$.

PROOF. The existence and uniqueness of the optimal solution and Properties (2.3) and (2.5) follow from [5; Theorem 2]. Let \tilde{u} be the optimal solution of Problem (2.2). Then

 $|\tilde{u}|$ and min $(\tilde{u}, 1)$ are also feasible solutions of Problem (2.2). By the relations :

 $D(|\tilde{u}|) \leq D(\tilde{u})$ and $D(\min(\tilde{u}, 1)) \leq D(\tilde{u})$

([5; Lemma 2]) and by the uniqueness of the optimal solution of Problem (2.2), we obtain $\tilde{u} = |\tilde{u}| = \min(\tilde{u}, 1)$, so that $0 \le \tilde{u}(x) \le 1$ on X.

The following result was shown in [4; Theorem 3.1].

LEMMA 2.3. The function k_a has the following properties :

(2.6) $k_a(a) = D(k_a);$

- (2.7) $k_a(b) = k_b(a)$ for every $a, b \in X_0$;
- (2.8) $\Delta k_a(x) = -\varepsilon_a(x) + \varepsilon_{x_0}(x) \text{ for } x \in X.$

LEMMA 2.4. $k_a/k_a(a)$ is the optimal solution for $d(x_0, a)$ and $\lambda(x_0, a) = k_a(a)$. Furthermore,

 $0 \leq k_a(x) \leq k_a(a)$ on X.

PROOF. Let us put $\tilde{v} := k_a/k_a(a)$. Then by Lemma 2.3

$$\tilde{v}(x_0) = 0$$
, $\tilde{v}(a) = 1$, $D(\tilde{v}) = 1/D(k_a) = 1/k_a(a)$.

For any $u \in D(N)$ such that $u(x_0) = 0$ and u(a) = 1, we have

$$D(u, \tilde{v}) = D(u, k_a)/k_a(a)^2 = 1/k_a(a) = D(\tilde{v})$$

by (K.1). Since $|D(u, \tilde{v})| \le [D(u)]^{1/2} [D(\tilde{v})]^{1/2}$, we obtain $D(\tilde{v}) \le D(u)$. Hence $d(x_0, a) = D(\tilde{v})$. By (2.4), $0 \le \tilde{v} \le 1$ on X, or $0 \le k_a(x) \le k_a(a)$ on X.

We shall prove

THEOREM 2.5. Let $a, b \in X_0$ be two distinct nodes and put $u_{ab} := k_b - k_a$. Then v_{ab} := $[u_{ab} - u_{ab}(a)]/D(u_{ab})$ is the optimal solution for d(a, b) and the following relation holds :

$$\lambda(a, b) = D(u_{ab}) = k_a(a) - 2k_a(b) + k_b(b).$$

PROOF. Note that $D(v_{ab}) = 1/D(u_{ab}) < \infty$, $v_{ab}(a) = 0$. By the relation

$$u_{ab}(b) - u_{ab}(a) = k_b(b) - 2k_a(b) + k_a(a) = D(u_{ab}),$$

we have $v_{ab}(b) = 1$. Let $u \in D(N)$ satisfy u(a) = 0 and u(b) = 1. Then $u' = u - u(x_0) \in D(N; x_0)$ and

$$D(u, v_{ab}) = D(u, u_{ab})/D(u_{ab})$$

= [D(u', k_b) - D(u', k_a)]/D(u_{ab})
= [u'(b) - u'(a)]/D(u_{ab})

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$$=1/D(u_{ab})=D(v_{ab})$$

by (K.1). Thus $D(v_{ab}) \leq D(u)$ and v_{ab} is the optimal solution for d(a, b).

By Lemma 2.4 and Theorem 2.5, we have

THEOREM 2.6. For distinct three nodes x_0 , a and b.

$$\lambda(a, b) = \lambda(x_0, a) + \lambda(x_0, b) - 2k_a(b).$$

Since $k_a(x) \ge 0$ by Lemma 2.4, we obtain

THEOREM 2.7. Let a, b and c be three distinct nodes. Then the triangle inequality (2.1) holds.

§ 3. Extremum problems related to Green functions

In this section, we always assume that N is of hyperbolic type. Let a and b be two distinct nodes and consider the following extremum problem similar to Problem (2.2):

(3.1) Minimize D(u)

subject to $u \in D_0(N)$ and u(b) - u(a) = 1.

Denote by $\rho(a, b)$ the value of Problem (3.1). We have

THEOREM 3.1. Let $u_{ab}^* := g_b - g_a$ and $v_{ab}^* := u_{ab}^* / D(u_{ab}^*)$. Then v_{ab}^* is an optimal solution of Problem (3.1).

PROOF. Clearly, $v_{ab}^* \in D_0(N)$ and $D(v_{ab}^*) = 1/D(u_{ab}^*)$. We have

$$u_{ab}^{*}(b) - u_{ab}^{*}(a) = g_{b}(b) - 2g_{a}(b) + g_{a}(a)$$
$$= D(g_{b} - g_{a}) = D(u_{ab}^{*})$$

by (G.1) and the symmetry of $g_a(b)$ (cf. [6; Theorem 3.3]). Therefore v_{ab}^* is a feasible solution of Problem (3.1). Let u be any feasible solution of Problem (3.1). By (G.1), we have

$$D(u, v_{ab}^*) = [D(u, g_b) - D(u, g_a)]/D(u_{ab}^*)$$
$$= [u(b) - u(a)]/D(u_{ab}^*)$$
$$= 1/D(u_{ab}^*) = D(v_{ab}^*).$$

By the relation : $|D(u, v_{ab}^*)| \le [D(u)]^{1/2} [D(v_{ab}^*)]^{1/2}$, we obtain $D(v_{ab}^*) \le D(u)$. Thus $\rho(a, b) = D(v_{ab}^*)$ and v_{ab}^* is an optimal solution of Problem (3.1).

Related to Problems (2.2) and (3.1), we consider extremum problems on the sets of flows as in [5].

Let a and b be distinct nodes. We say that $w \in L(Y)$ is a flow from a to b if it satisfies

(3.2)
$$\sum_{y \in Y} K(x,y) w(y) = 0 \text{ for } x \in X - \{a, b\}$$

(3.3)
$$I(w) := -\sum_{y \in Y} K(a, y) w(y) = \sum_{y \in Y} K(b, y) w(y).$$

We call I(w) the strength of w.

Denote by F(a, b) the set of all flows from a to b and by $F_2(a, b)$ the closure of $F(a, b) \cap L_0(Y)$ in the Hilbert space $L_2(Y; r)$.

Let us consider the following extremum problems :

(3.4) Minimize H(w)

subject to $w \in F_2(a, b)$ and I(w) = 1.

(3.5) Minimize H(w)

subject to $w \in F(a, b)$ and I(w) = 1.

Denote by $d_0^*(a, b)$ and $d^*(a, b)$ the values of Problems (3.4) and (3.5) respectively. We have by [5; Theorem 11]

LEMMA 3.2. $d(a, b)d_0^*(a, b) = 1$.

We shall prove

THEOREM 3.3. $\rho(a, b)d^*(a, b) = 1$ holds and $\tilde{w} := -d(g_b - g_a)$ is an optimal solution of Problem (3.5).

PROOF. Let $w \in F(a, b) \cap L_2(Y; r)$ and $u \in D_0(N)$ satisfy the conditions : I(w) = 1and u(b) - u(a) = 1. Then

$$1 = u(b) - u(a) = \sum_{x \in X} u(x) \sum_{y \in Y} K(x, y) w(y)$$
$$= \sum_{y \in Y} w(y) \sum_{x \in X} K(x, y) u(x)$$
$$\leq [H(w)]^{1/2} [D(u)]^{1/2}$$

by the same reasoning as in the proof of [5; Theorem 5]. Therefore we have

$$1 \leq d^*(a, b)\rho(a, b).$$

Since $\tilde{w} \in F(a, b)$ and $I(\tilde{w}) = 1$, we have

$$d^*(a, b) \leq H(\tilde{w}) = D(g_b - g_a) = \rho(a, b)^{-1}.$$

This completes the proof.

THEOREM 3.4. $d(g_b-g_a) \in F_2(a, b)$ if and only if $d^*(a, b) = d_0^*(a, b)$ holds.

PROOF. Note that $d^*(a, b) \le d_0^*(a, b)$ holds in general. The "only if" part is clear. We prove the "if" part. There exists an optimal solution w_1^* of Problem (3.4). We see by [5;

Lemma 11] that there exists $v^* \in \mathbf{D}(N)$ such that $w_1^* = -dv^*$. Let $\tilde{w} := -d(g_b - g_a)$ and $w_2^* := \tilde{w} - w_1^*$. Then we see easily that there exists $h^* \in \mathbf{D}(N)$ such that $w_2^* = -dh^*$. Since $I(\tilde{w}) = I(w_1^*) = 1$, we have

$$\Delta h^*(x) = -\sum_{y \in Y} K(x, y) w_2^*(y) = 0,$$

so that $h^* \in HD(N) := \{u \in D(N); \Delta u = 0\}$. Since $g_b - g_a \in D_0(N)$, we have by [6; Lemma 1.3]

$$< \tilde{w}, w_2^* > = D(g_b - g_a, h^*) = 0,$$

so that $\langle w_1^*, w_2^* \rangle = -H(w_2^*)$. Therefore

$$d^*(a, b) = H(\tilde{w}) = <\tilde{w}, w_1^* >$$

= $H(w_1^*) - H(w_2^*) = d_0^*(a, b) - H(w_2^*).$

If $d^*(a, b) = d_0^*(a, b)$ holds, then $H(w_2^*) = 0$, so that $w_2^* = 0$, or equivalently, $\tilde{w} = w_1^* \in F_2(a, b)$.

§4. Miscellaneous remarks

Let us study some properties of the function defined by

$$\varphi(x) := k_x(x) = \lambda(x_0, x) \text{ for } x \in X_0;$$

$$\varphi(x_0) := 0.$$

Let us introduce the following coefficients :

$$\begin{split} t(x, a) &:= \sum_{y \in Y} r(y)^{-1} |K(x, y)K(a, y)| \quad \text{for } x \neq a, \\ t(a, a) &= 0, \\ t(a) &:= \sum_{y \in Y} r(y)^{-1} |K(a, y)|. \end{split}$$

Then we have $t(a) = \sum_{x \in X} t(x, a), t(x, a) = t(a, x)$ and

(4.1)
$$\Delta u(a) = -t(a)u(a) + \sum_{x \in X} t(x, a)u(x).$$

THEOREM 4.1. The following relations hold :

(4.2)
$$\Delta \varphi(a) = \sum_{x \in X} t(x, a) \lambda(x, a) - 2 \text{ for } a \neq x_0$$

(4.3) $\Delta \varphi(x_0) = \sum_{x \in X} t(x, x_0) \lambda(x_0, x).$

PROOF. (4.3) follows from (4.1) and $\varphi(x_0) = 0$. To prove (4.2), let $a \in X_0$. By Lemma 2.4 and Theorem 2.6, for $x \neq a$

(4.4)
$$\varphi(x) = \lambda(a, x) - k_a(a) + 2k_a(x).$$

We have by (4.1) and (4.4)

$$\Delta \varphi(a) = -2t(a)k_a(a) + \sum_{x \in X} t(x, a)\lambda(a, x)$$
$$+ \sum_{x \in X} t(x, a)2k_a(x)$$
$$= \sum_{x \in X} t(x, a)\lambda(a, x) + 2\Delta k_a(a)$$
$$= \sum_{x \in X} t(x, a)\lambda(a, x) - 2.$$

This completes the proof.

In the case where N is the 2-dimensional lattice domain with r=1, it is well-known as in [3] that $\lambda(x, a) = 1/2$ if x is a neighboring node of a. Since t(x, a) = 1 if x is a neighboring node of a, we see that

$$\sum_{x\in X} t(x,a)\lambda(x,a) = 2.$$

Flanders [3] called $\varphi(x)$ the fundamental solution.

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